# **LEAPER Visual Inspection Solutions** for Li-ion Battery



## Platform software, full process section inspection coverage

In the raw material, to realize the detection of diaphragm, aluminum-plastic film, etc; In the front section, responding to inspection needs such as coating and die-cutting; In the middle section, responding to visual inspection of laminated winding; In the back section, to complete the battery module components welding quality inspection and finished product appearance inspection.



### Multiple core technologies, focus on visual inspection

With rich experience in measurement and positioning as well as defect detection cases, the self-developed traditional general vision platform with AI can solve the inspection problems and achieve accurate positioning and measurement while improving inspection accuracy. LEAPER's configurable vision systems are widely used in all process stages of lithium battery production. At present, we can provide customized vision inspection solutions for the raw material section-defect detection of copper, aluminum foil and diaphragm; the production section-defect detection and width measurement of coating and slitting process; the core section-die-cutting machine, stacker, cut-and-stack machine; and the pack section-vision-guided welding, The core section-die cutter, laminator, cut and stack machine; pack section-vision guided welding, etc., we can provide customized vision inspection solutions for customers.



### **Coating Process**

Coating Process



Roll measurement and surface defect detection

#### Software Interface



Inspection Content: Roll surface detection, Film width measurement, Tab width measurement, Ceramics width measurement. Defect detection accuracy: 0.3mm Measurement accuracy: 0.05mm/pixel



Algorithm Execution Time: ≤0.5s/pcs Major Components: Line scan camera, Industrial lens, High intensity line scan lights, Industrial intelligent processing center.

### **Cell Production Process**



**Cell Production Process** 



Software Interface

#### Full-size Inspection of Electrode after Die Cutting



Installation Process: Tab welding machine Installation Position: after slitting Inspection Width: 250mm\*250mm Camera Model: 890W Number of Cameras: 3 Accuracy: 50µm/pixel Inspection Requirements: size ± 0.1mm, angle ± 0.15° Inspection Type: Measurement

#### Surface Inspection of Stacking

Installation Process: Slitting & stacking integrated machine Installation Position: after slitting Inspection Width: 289mm\*100mm Camera Model: 4K Number of Cameras: 2 Accuracy: 28µm/pixel Inspection Content: (1) Appearance detection: R-corner trimming, dog-ear judgment, nick detection, etc. (2) Defect detection: hole, smudge, scratch, burr, etc. Detection Accuracy: ≥0.3mm Detection Speed: ≤0.3s Core Components: line scan camera, Industrial lens, High performance line light source



#### **Positioning & Correction Detection**



Accuracy Requirements: ±0.05mm Beat: ≤0.15s

#### **Overhang Detection**



Accuracy Requirements: ±0.1mm Beat: ≤0.15s

#### **Pouch Cell Surface Defect Detection**



Inspection Content: Smudge, scratch (strips), creases, swollen, crack, wound(face) Detection Accuracy: 0.5mm/pixel Detection Speed: ≤0.5s Core Components: 20MP area scan cameras

#### **Stick Detection of Pouch Cell**



Inspection Content: Tape position, whether glued Detection Accuracy: 0.05mm/pixel Detection Speed: ≤0.2s Core Components: 5MP area scan cameras

### Li-ion Battery Module/PACK



Li-ion Battery Module/PACK



Software Interface

# Welding Guidance Plans for Cap Plate of Square Shell Battery Module



**Inspection Content:** Visual guide for cathode&anode laser welding, explosion-proof valve laser pre-welding and full welding, lead tag laser welding

Visual Detection Accuracy: 0.05mm/pixel

Detection Speed: ≤0.2s ( excluding laser processing time ) Core Components: Area scan cameras, Red ring light

### **Defect Detection of Battery Cap**



**Inspection Content:** Coordinate positioning of cap nails to guide laser welding

**Visual Detection Accuracy:** Static repetitive positioning precision < 0.5 pixels, dynamic repetitive positioning precision < 2 pixels

Detection Speed: ≤0.2s ( excluding laser processing time ) Core Components: Area scan cameras, Ring light

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